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# Report

Tool für die Bewertung von Eingebetteten Systemen

Design und Integration einer Analyseverfahren in SymTA/S

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## Abstract

A analysis method for embedded systems, called Real Time Calculus (RTC), has been developed at the institute TIK of ETH Zurich in the last years. The method has not been embedded in a graphical tool so far and therefore TIK has been looking for a possible implementation.

A tool, called SymTA/S, to analyze embedded systems based on certain known analysis methods has been developed at TU Braunschweig. This tool fulfills the requirement of the TIK methods and therefore the idea was to integrate the TIK method into SymTA/S.

This semester thesis shows how this implementation has been done. It starts with an evaluation of the requirements for the tool and gives then a detailed explanation about the chosen generic way of integrating the TIK method into this existing tool.

The major part of this thesis explains the exact implementation and the concepts behind it and further some details about the calculation flow.

Finally, it provides a short user guide which describes the usage of the TIK analysis method specific parts of the SymTA/S tool. Furthermore, it shows an analysis example.

## Contents

<b>1</b>	<b>Introduction</b>	<b>5</b>
1.1	Problem Description . . . . .	5
1.1.1	Subject . . . . .	5
1.1.2	Semester Thesis Task . . . . .	5
1.2	Approach . . . . .	5
1.2.1	Understanding Analysis Methods . . . . .	5
1.2.2	Define Specifications . . . . .	5
1.2.3	Get to Know SymTA/S . . . . .	5
1.2.4	Implementation . . . . .	5
1.2.5	Documentation . . . . .	5
1.3	Related Work . . . . .	6
1.3.1	Analysis Method from TIK . . . . .	6
1.3.2	SymTA/S . . . . .	6
<b>2</b>	<b>Tool Specifications</b>	<b>7</b>
2.1	Drawing Curves . . . . .	7
2.1.1	Functionality . . . . .	7
2.1.2	Coordinate Plan . . . . .	7
2.1.3	Upper and Lower Curve . . . . .	7
2.2	Import and Export Format . . . . .	7
2.3	Data Structure . . . . .	8
2.3.1	Source Task . . . . .	8
2.3.2	Regular Task . . . . .	8
2.3.3	Sink Task . . . . .	8
2.4	Curve Types . . . . .	8
2.4.1	Alpha Curve . . . . .	9
2.4.2	Alpha Prime Curve . . . . .	9
2.4.3	Beta Curve . . . . .	9
2.4.4	Beta Prime Curve . . . . .	9
2.5	Resources . . . . .	9
2.5.1	Scheduling Policies . . . . .	9
2.6	Execute Analysis . . . . .	10
<b>3</b>	<b>SymTA/S</b>	<b>11</b>
<b>4</b>	<b>The Idea of Generic Objects and Libraries</b>	<b>13</b>
4.1	General Structure . . . . .	13
4.2	Libpreferences.xml . . . . .	13
4.3	SymTA/S Core . . . . .	14
4.4	Data structure . . . . .	14
4.4.1	Generic Resource . . . . .	14
4.4.2	Generic Process . . . . .	14
4.4.3	Further Generic Data Structure Classes . . . . .	15
4.5	GUI . . . . .	15
4.6	Analysis . . . . .	15
<b>5</b>	<b>Implementation</b>	<b>16</b>
5.1	GUI . . . . .	16
5.1.1	Curve Drawer . . . . .	16
5.1.2	Task and Resource Containers . . . . .	18
5.2	Data Structure . . . . .	19
5.2.1	Class Curve . . . . .	20
5.2.2	Class CurveSegment . . . . .	20
5.2.3	Class ProcessTIK . . . . .	20
5.2.4	Class ResourceTIK . . . . .	21
5.2.5	Interface Drawable . . . . .	22
5.3	Analysis . . . . .	23

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5.3.1	Calculation Flow . . . . .	23
5.3.2	Class Analysis . . . . .	24
5.3.3	Scheduler . . . . .	26
5.3.4	FPS Scheduler . . . . .	27
5.3.5	TMDA Scheduler . . . . .	28
5.3.6	Class WCET_calculation . . . . .	29
5.3.7	Package Singlenode . . . . .	29
<b>6</b>	<b>Short user manual</b>	<b>30</b>
6.1	How To Use? . . . . .	30
6.1.1	Tasks and Resources . . . . .	30
6.1.2	Curve Drawer . . . . .	32
6.2	Analysis Example . . . . .	33
<b>7</b>	<b>Outlook</b>	<b>36</b>
<b>8</b>	<b>Summary</b>	<b>37</b>
<b>A</b>	<b>Acknowledgements</b>	<b>38</b>
<b>B</b>	<b>Bibliography / References</b>	<b>39</b>
<b>C</b>	<b>Example of a Curve XML File</b>	<b>40</b>
<b>D</b>	<b>Libpreferences.xml</b>	<b>41</b>

## List of Figures

1	Example for Fixed Priority Scheduling . . . . .	8
2	Print Screen of SymTA/S Tool from TU Braunschweig, source: [11]. . . . .	11
3	Structure of Library Idea . . . . .	13
4	UML Diagram for the Generic Resource . . . . .	15
5	UML Diagram for the Generic Process . . . . .	15
6	Class Structure . . . . .	16
7	Coordinate Transformation . . . . .	17
8	Coordinate Rotation . . . . .	18
9	Source Tasks and Appendant Curve Drawer Windows . . . . .	19
10	UML Diagram of Data Structure . . . . .	19
11	Curve Segments of a Staircase Function . . . . .	20
12	UML Diagram of Process Structure . . . . .	21
13	UML Diagram of Resource Structure . . . . .	22
14	UML Diagram of Interface Drawable . . . . .	22
15	Example to Explain the Calculation Flow Implemented in the Library . . . . .	23
16	Architecture of the Method Analysis . . . . .	24
17	Example of a Deadlock . . . . .	25
18	Architecture of the Error Handling . . . . .	26
19	UML Diagram of the Environment of Scheduler Class . . . . .	27
20	Weighted Beta Curves with the Option <i>Evaluate Window Size</i> and a Window Size of 1.0 . . . . .	29
21	Weighted Beta Curves without the <i>Option Evaluate Window Size</i> . . . . .	29
22	Properties of a Source Task . . . . .	30
23	Properties of a Regular Task . . . . .	31
24	Properties of a Sink Task . . . . .	31
25	Properties of a Resource . . . . .	32
26	Curve Drawer Window . . . . .	32
27	Simulation Example . . . . .	33
28	Alpha Curves Task T1 . . . . .	33
29	Alpha Curves Task T3 . . . . .	34
30	Beta Curves Resource R0 and R1 (Upper and lower curves are congruent.) . . . . .	34
31	Alpha Prime Curves Task T2 . . . . .	35
32	Alpha Prime Curves Task T5 . . . . .	35

# 1 Introduction

## 1.1 Problem Description

### 1.1.1 Subject

During the last year researchers at the institute IDA (Institut für Datentechnik und Kommunikationsnetze) of TU Braunschweig developed a tool, which can be used to analyze embedded systems consisting of processors and communication devices. The tool is called SymTA/S, which stands for Symbolic Timing Analysis for Systems. It implements various analysis methods e.g. the methods described in [3].

In the same time an analytical method has been developed at the computer engineering and networks laboratory (TIK) of Swiss Federal Institute of Technology Zurich (ETH) to evaluate embedded system. This method allows to investigate on performance parameters [1], and has been applied to network processors [2, 7].

### 1.1.2 Semester Thesis Task

The analysis methods developed at TIK should be integrated into SymTA/S, the tool developed at TU Braunschweig. The methods should be implemented in a separate library. The choice of which analysis method to use in SymTA/S, can be made in a separate XML document as [9] exemplarily shows.

## 1.2 Approach

The semester thesis has been split into several subtasks. The subtasks have been solved in the following sequence.

### 1.2.1 Understanding Analysis Methods

The methods which have been developed at TIK are the core of the library, which has to be developed during this thesis. Therefore it has been very important to gain an overall understanding of these analysis methods.

### 1.2.2 Define Specifications

The next step was to write clear specifications for the tool. They describe what the tool has to fulfill. The resulting specifications are part of this report and can be found in Section 2.

### 1.2.3 Get to Know SymTA/S

The library has to fit on an existing tool. A clear understanding of SymTA/S from a user point of view is therefore the next step. But not only understanding how the user uses the tool, rather get along with the existing programming work, how the interface looks like and how we can use the existing tool and adapt it to our requirements, was the next step.

### 1.2.4 Implementation

The main part of this thesis was to implement the requirements and the adaption onto SymTA/S. The software has been tested during the programming work.

### 1.2.5 Documentation

The documentation has been written with  $\text{\LaTeX}$  and contains specifications, implementation and further information. The usage section contains a short user guide. The conclusions and an outlook of further work and research can be found in Section 7, the summary in Section 8 and the bibliography and acknowledgments in the appendix.

The main effort has been made for developing a user friendly tool, which fits all the requirements.

### 1.3 Related Work

#### 1.3.1 Analysis Method from TIK

There have been published several papers about the analysis method *Real Time Calculus* (RTC) from TIK. Among others there are [1], [2], [4] and [7], which describe the method which has been developed at TIK.

#### 1.3.2 SymTA/S

A user guide about how to use SymTA/S has been published by the institute IDA of TU Braunschweig [11]. The papers [3], [5] and [6] give information about the implemented analysis methods. The project web page at [10] gives more information about the SymTA/S project and contains a lot of papers about analysis methods, too.

## 2 Tool Specifications

This section summarizes the specifications which have been made from a user point of view. This means the specifications do not give any ideas, how user requirements as for example 'drawing a curve' are solved from a technical respectively implementing point of view. This section describes the requirements, we have on the tool.

The SymTA/S tool is enlarged by a library as described in Section 1. The requirements described in this section concern this library. The library is programmed as generic as possible to simplify changes. Furthermore there exists a clear interface to use it within other applications.

### 2.1 Drawing Curves

The idea is to have a separate frame, where the user can input a curve pair consisting of an upper and a lower curve graphically.

#### 2.1.1 Functionality

A curve is divided into curve segments. The following functionality is provided by the tool:

- drawing a curve segment
- selecting a curve segment
- shifting a curve segment
- deleting a curve segment

Selecting, shifting and deleting can also be applied on several curve segments.

The user has also the possibility to show the coordinates of one or several curve segments. When curves are drawn, shifted or selected these coordinates are automatically adjusted.

#### 2.1.2 Coordinate Plan

The coordinate plan consists of two axis and the first quadrant is shown. The drawing ground is divided into squares. Each square is divided by 10 in both axis directions where a start or end curve point can be placed.

#### 2.1.3 Upper and Lower Curve

Each curve  $(\alpha, \alpha', \beta, \beta')$ <sup>1</sup> consists of two parts, a lower curve and an upper curve as discussed in [1]. In the drawing window the lower and upper part of the curve are drawn in different colors, can be saved and loaded separately and are also handled separately. If for example the user draws a lower and upper curve and then loads an upper curve from an XML file<sup>2</sup> the upper curve is overwritten but the lower one remains unchanged.

## 2.2 Import and Export Format

Curves can be imported and exported to and from SymTA/S, using the XML format. The format is defined in the DTD file in [8].

For upper and lower curve separate XML files are created and read. The type (upper or lower) is also defined within the XML file. Furthermore the four illustration variables<sup>3</sup> are also saved in the XML document.

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<sup>1</sup>Alpha, alpha prime, beta and beta prime stand for arrival, arrival prime, service and service prime curves. To simplify this name we use alpha and beta as they are defined in [1].

<sup>2</sup>XML files and their usage are described in Section 2.2.

<sup>3</sup>xgrid and ygrid indicates the number of squares in the drawing area per axes. Whereas xunit and yunit represents the unit of one square. These four variables do not have to be defined in import files.

## 2.3 Data Structure

Figure 1 shows a possible simplified structure of two processes relocated to one resource.

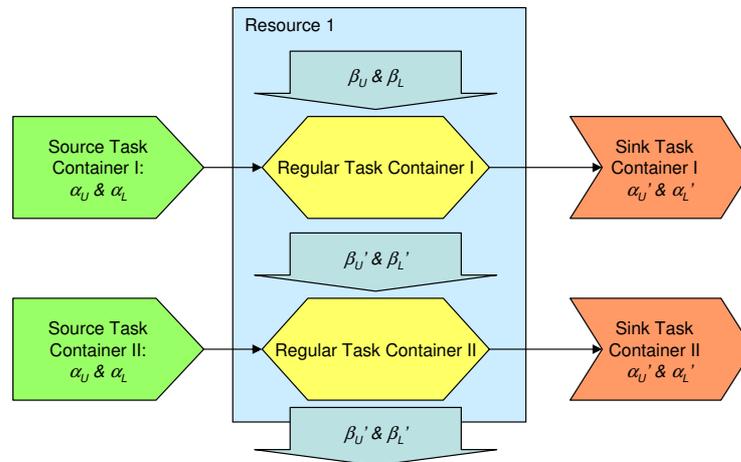


Figure 1: Example for Fixed Priority Scheduling

Since we use the data structure and graphs, which are already implemented in SymTA/S, we have to fit the TIK analysis method to this data structure and graphs of TU Braunschweig.

### 2.3.1 Source Task

The source task contains only the alpha curves. In the tasks internal frame there is a button *Edit Alpha Curves*.

### 2.3.2 Regular Task

The regular task contains all four curve pairs. These are the alpha curves, beta curves, alpha prime curve and beta prime curve. In the Tasks internal frame there are four buttons *Show Alpha Curves*, *Show Beta Curves*, *Show Alpha Prime Curves* and *Show Beta Prime Curves*. (No curves can be drawn on a regular task.) On the regular task the curves can only be viewed, but not edited. How to edit alpha curves is described in Section 2.3.1 and for beta curves see Section 2.5. For more details compare also the Section 2.4.

The *Worst Case Execution Time* (WCET) is a factor which influences the alpha and alpha prime curves. This time is related to a certain task and can therefore be entered on the regular task internal frame.

In this first version of the library, the WCET is implemented as a factor, by which the alpha curves are multiplied and the result is divided after calculating the resulting alpha prime curves.

### 2.3.3 Sink Task

The sink task contains only the resulting alpha curves. In the Tasks internal frame there is a button *Show Alpha Prime Curves*.

## 2.4 Curve Types

The various curves which are implemented are described in this section. Furthermore the way to enter or to show them is described in this section, too.

### 2.4.1 Alpha Curve

The alpha curve pair is placed on a source task. For every alpha curve pair there is a separate source task.<sup>4</sup>

To enter the curves, the user can click on the source in the editor internal frame and then can click on the *Edit Alpha Curves* button in the task internal frame.

### 2.4.2 Alpha Prime Curve

One of the outcomes of the analysis is the alpha prime curve pair. The user can see the resulting alpha curves after executing a global analysis<sup>5</sup>.

Within the tasks internal frame the user can click on the *Show Alpha Prime Curves* button. In a new window he can see the results and by clicking on the save icon he can save them to XML files. The alpha prime curves on a regular task show the local result, the one ones the sink task represent the global result.

### 2.4.3 Beta Curve

Beta curve pairs are related to resources. A certain resource has a certain amount of capacity. Therefore the curves are not implemented as the alpha curves in a separate task, but moreover there are directly related to a certain resource.

Consequently the beta curve pair is entered by pressing the *Edit Beta Curves* button in the resource internal frame, after selecting the resource.

### 2.4.4 Beta Prime Curve

The resulting beta prime curves can be viewed on the regular task. The local beta prime curves can be found on the regular task, the global ones on the resource.

The local beta prime curve, can be viewed by selecting the regular task in the editor internal frame and then pressing the *Show Beta Prime Curves* button. A new window with the resulting beta prime curve pair opens after pressing this button. To look at the resulting beta prime curves of a resource, the button *Show Beta Prime Curves* in the resource internal frame shows the results.

## 2.5 Resources

The resource internal frame shows the created resources. For each resource a scheduling policy can be allocated, which are described in Section 2.5.1. Each resource contains a service curve (so called beta curve) which can be entered by pressing the *Edit Beta Curves* button.

### 2.5.1 Scheduling Policies

The first version of this tool supports two scheduling policies, which are described in the subsequent paragraphs. The architecture will be chosen as generic as possible to simplify the process of adding new scheduling policies. The scheduling policy can be chosen in the resource internal frame. Whereas parameters concerning a policy which are related to tasks can be input in the task internal frame, after mapping a task to a resource and having already chosen a certain scheduling policy.

#### Fixed Priority Scheduling (FPS)

Fixed priority scheduling is a policy which allocates the resource to the task according to the priority of the tasks. Therefore each task requires a priority. The priority can be entered in the task internal frame as described above.

<sup>4</sup>In Figure 1 you can find two source task and each contains both the alpha curves (upper and lower).

<sup>5</sup>The analysis process is described in Section 2.6.

**Time Division Multiple Access (TDMA)**

The Time Division Multiple Access policy gives each task a certain percentage of the available resource. The percentage is related to the task and therefore can be entered in the task internal frame, as well.

**2.6 Execute Analysis**

To execute the calculation of the resulting curves, memory consumption and delay for each task the existing icon *perform global analysis step* can be used. By pressing this button all curves are calculated and circular relations are solved. After finishing the calculation the user can look at the curves and save them individually if requested.



#### 4. **Tasks Window**

In the upper right corner the user can enter the parameters of a task. There exist three different tasks, which are *Source Tasks*, *Regular Tasks* and *Sink Tasks*. Depending on the task the window shows a different content. The mapping of regular tasks on resources can be done as well within this window.

#### 5. **Resource Window**

The resource window contains the parameters of the hardware resources. Here the scheduler can be chosen and further parameters can be defined in this window.

#### 6. **Event Streams Window**

In the lower right corner the user can define the event stream parameters.

#### 7. **Architecture Window**

Whereas the mapping of tasks on resources is done in the tasks window, the resulting architecture is shown in the architecture window. The user can see here the names of the tasks and resources and which task is mapped on which resource. Furthermore the scheduling algorithms are displayed for each resource.

#### 8. **Output window**

The output window in the lower left corner displays the debugging messages. This is the main communication channel between the user and the tool to display important messages.

Herewith we mentioned all parts of the program which are relevant for us.

## 4 The Idea of Generic Objects and Libraries

This section describes how the implementation of the TIK analysis method into the SymTA/S tool is done and what the idea of the library is.

### 4.1 General Structure

Figure 3 shows the SymTA/S tool. The core of the tool can be found in the middle of the figure. This core consists of the main parts of the program which are not dependent on the analysis method. This is for example the graphical *Editor* window where the user can draw the tasks and connect them. This window can be used independently of the analysis method and is therefore part of the SymTA/S core. One of the reason to implement the TIK method into the SymTA/S tool is exactly to use this functionality which is provided by the SymTA/S core and which can be used in each analysis method.

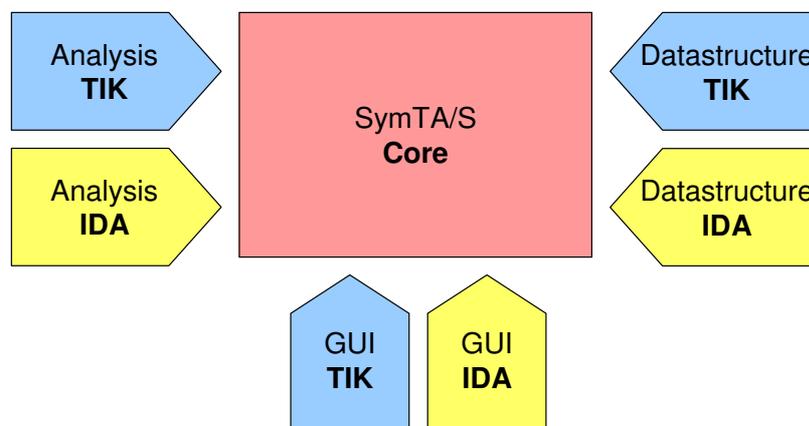


Figure 3: Structure of Library Idea

The modules around the core in Figure 3 show the part of the tool, which can be chosen depending on the analysis method. This part is split into three subparts:

- the graphical user interface (GUI)
- the data structure which is needed depending on the analysis method
- and the analytical method itself.

The user can decide which analysis method he wants to use to do his evaluations. If the user wants to use the TIK analysis method, he chooses the TIK packages *GUI TIK*, *Datastructure TIK* and *Analysis TIK*, otherwise he chooses the IDA packages.

The SymTA/S core and the IDA package names start with `org.spiproject`, whereas the TIK package names start with `ch.ethz.ee.tik.rtc`<sup>7</sup>.

### 4.2 Libpreferences.xml

The selection of the requested parts, respectively the analysis method, is done in a separate XML file, which is called `libpreferences.xml` and which can be found in the folder `org.spiproject`. This paragraph explains the structure of this file.

The root element `<Symta-S>` contains four elements, which are:

**<gui>** In the GUI part pointers to the classes which are used for GUIs are defined.

**<datastructure>** This element contains the classes which are used for the data structure.

<sup>7</sup> *rtc* stands for *Realtime Calculus*, the name of the TIK analysis method.

**<analysis>** The analysis element references the analysis class.

**<settings>** And the last element contains further settings, for example which buttons are used.

An example is given in Appendix D. It shows the file as it is used in the current version of the tool.

During run time the program reads the XML file and decides which packages respectively classes are loaded together with the SymTA/S core.

### 4.3 SymTA/S Core

The *Editor Window* is part of the SymTA/S core. The user draws here the tasks and connects them. The *Architecture Window* is as well part of the SymTA/S core and can therefore be used for each analysis method, as the editor window. All tasks and appropriate resources in SymTA/S are stored in a graph, which extends the open-source library `JGraph`. The class `ApplicationGraph` in the package `org.spiproject.application` represents this graph and herewith is part of the core program. A reference to the application graph can be initialized from every class in the program. This means we can access the tasks and resource from every location of the program. Within the analysis we can store for example the reference to the application graph in the variable `ag`:

```
ApplicationGraph ag = parent.getMainGUI().getApplicationGraph();
```

Now we can use `ag` to get a map with all resources the user has drawn in the editor window:

```
Map resourceMap = ag.getCpuMap();
```

The application graph is a very powerful tool to use the possibility SymTA/S offers.

### 4.4 Data structure

The data structure is the part of the library where the classes which hold the data are defined. The following subsections explain details about the parts which are chosen in the `libpreferences.xml` file.

#### 4.4.1 Generic Resource

The structure which allows to choose between IDA and TIK classes (dependent on the analysis method), is described in this paragraph for the resource exemplarily. This generic concept can also be applied to new methods.

Because all libraries rely on their own datastructures, we have to implement the interface `GenericResource` for the classes `ResourceIDA` and `ResourceTIK`. The application graph accesses the datastructures through this interface. Figure 4 shows an UML diagram<sup>8</sup> of the dependencies of the resource. The package `org.spiproject.interface.datastructure` contains the public interface, called `GenericResource`, which is part of the core SymTA/S tool. The interface requires certain methods to be implemented which are used in the application graph. Depending on the entries the user has written into the `libpreferences.xml` file, the corresponding resource is implemented, as Figure 4 shows. This means, if the user wants to use the `ResourceTIK` he writes `ch.ethz.ee.tik.rtc.datastructure.ResourceTIK` into the `libpreferences.xml` file and the interface then loads the TIK resource.

#### 4.4.2 Generic Process

The same idea as described in Section 4.4.1 is also used for processes. The corresponding UML diagram is shown in Figure 5 and the interface `GenericProcess` can be found in package `org.spiproject.interfaces.datastructure`.

<sup>8</sup>The UML diagrams shown in this thesis are simplified to the elements which are relevant in the used context.

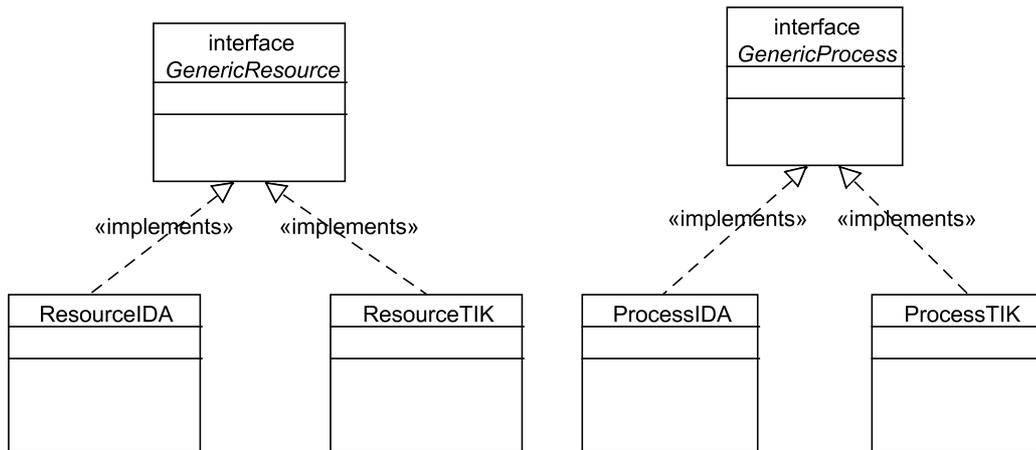


Figure 4: UML Diagram for the Generic Resource

Figure 5: UML Diagram for the Generic Process

#### 4.4.3 Further Generic Data Structure Classes

The XML file also defines `GenericInputPort`, `GenericOutputPort`, `GenericEventStream`, `GenericEventModel` as generic classes. Because we do not use an own derived version of this classes in our library at the moment, we do not explain them here in detail. The concept is the same as described in Section 4.4.1.

## 4.5 GUI

There are several graphical user interfaces (GUI). Therefore in the XML file the various GUIs can be defined, too. These are:

- `RegularTaskContainer`
- `SourceTaskContainer`
- `SinkTaskContainer`
- `ResourceContainer`
- `EventStreamContainer`

The first three represent the different tasks, the fourth a resource and the last one an event stream. The concept is the same as described in Section 4.4.1 and the generic classes can be found in package `org.spiproject.interfaces.gui`.

## 4.6 Analysis

Because the analysis is completely dependent on the analysis method, no common functions are defined in the core of SymTA/S and therefore the reference defined in the XML file points directly to the analysis class which implements `GenericAnalysis`. The interface `GenericAnalysis` can be found in package `org.spiproject.interfaces.analysis`. It is very simple as it just contains a single method `run()`, which is called by the SymTA/S core, if the user wants to analyse the specified system.

## 5 Implementation

This section describes the implementation of the library and the concepts behind it. It is divided into the three parts GUI, data structure and analysis.

### 5.1 GUI

This part will describe all implemented Graphical User Interfaces (GUI) which consist of internal frames and different panels.

#### 5.1.1 Curve Drawer

The *Curve Drawer* allows the user to draw or view upper and lower curves graphically in a separate frame.

#### General Class Structure

The curve drawer consists of four classes. The visible frame is represented by the class `DrawCurveWindow` which extends `JInternalFrame`. The area where the user can paint curves is represented by the class `DrawCurvePanel` which extends `JPanel`. `DrawCurvePanel` uses a class named `Grid` which paints the curves and the grid. The Class `GridDialog` which extends `JInternalFrame` opens a new frame and allows the user to change the grid properties. Figure 6 shows a simplified UML diagram of the class structure.

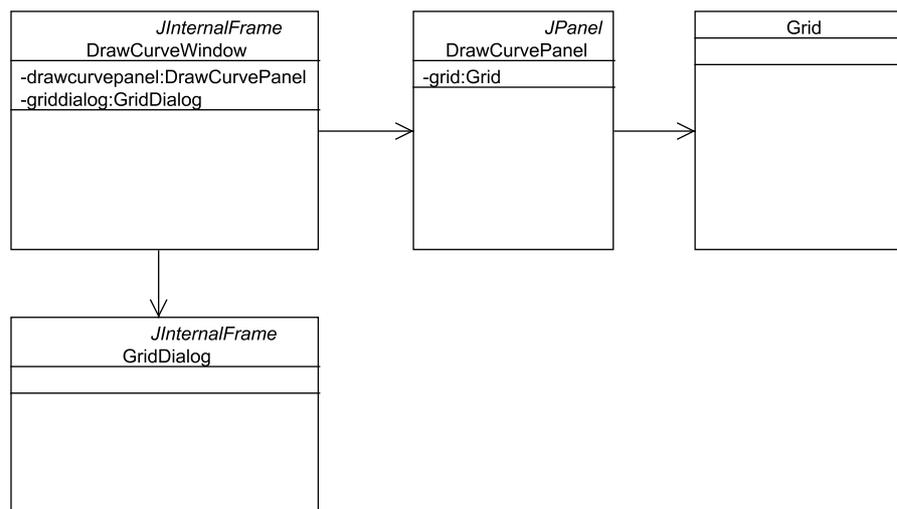


Figure 6: Class Structure

#### Class `DrawCurveWindow`

This class has a `BorderLayout`. In the north one can find a tool bar. All buttons and check boxes are placed in the tool bar. The `DrawCurvePanel` is placed in the center of the `JInternalFrame`. `DrawCurveWindow` uses a boolean variable named `editable` which is set in the constructor. The variable `editable` decides whether the user can draw curves in the frame or whether curves can only be shown.

#### Class `DrawCurvePanel`

`DrawCurvePanel` offers the whole functionality to draw curves. A `MouseListener` is waiting for user inputs and calls the appropriate methods. If the variable `selectmode` is set to 0, curve segments can be selected and moved. If `selectmode` equals 1, an upper curve can be drawn.

If `selectmode` equals 2, a lower curve can be drawn. The drawing happens by getting the x and y coordinates, when the mouse has been pressed, and getting the x and y coordinates, when the mouse has been dragged. The two points are now connected by a line. As soon as the user releases the mouse a curve segment can be stored. Selecting and shifting curve segments as well as storing them is delegated to the `Grid` class described in the next section.

The functionality to save curves into the data structure and reload them is also implemented in this class. To save curves into an XML file and to reload them, the methods from the `Curve` class are called.

Starting from java 1.4 the user is given the possibility to save the curves into a png file. In this case `DrawCurvePanel` draws all graphics into a image instead of the screen. The image then can be saved to a png file by using the java `ImageIO` class.

### Class Grid

This class is the most complex part of the Curve Drawer. It has to provide different methods used by `DrawCurvePanel`. As it would be too detailed to explain every method of the class some key spots are presented.

The user can determine how many squares in the x and the y direction he wants to be shown on the coordinate plan. The `Grid` class now draws the grid with its wished number of squares. If the size of the `DrawCurvePanel` changes, `Grid` is notified and the grid is drawn fitting to the new panel size.

The most important part of this class is to save and show the curves the user has entered. The curves are saved in a `Vector` in real coordinates<sup>9</sup>. Consequently a transformation from screen coordinates to real coordinates as shown in Figure 7 has to be done. The methods `addUpperCurveSegment` and `addLowerCurveSegment` get the coordinates of a curve segment the user has drawn in pixels, calculate the real coordinates by mirroring the coordinate plan and stretching it depending on the grid properties the user has chosen and save them into the `Vector`. To help the user entering curve segments, a square is divided into 10 subsquares in both axis directions. A start or end point can be placed on the angles of this subsquares. This subdivision is done by using following rounding function:

```
segment[i] = segment[i] * 10;
segment[i] = java.lang.Math.round(segment[i]);
segment[i] = segment[i] / 10;
```

When the `drawGrid` method is called, the curves are read from the `Vector`, the real coordinates are transformed to screen coordinates as shown in Figure 7 again and the curves then are drawn. If the user wants to select a curve segment, the

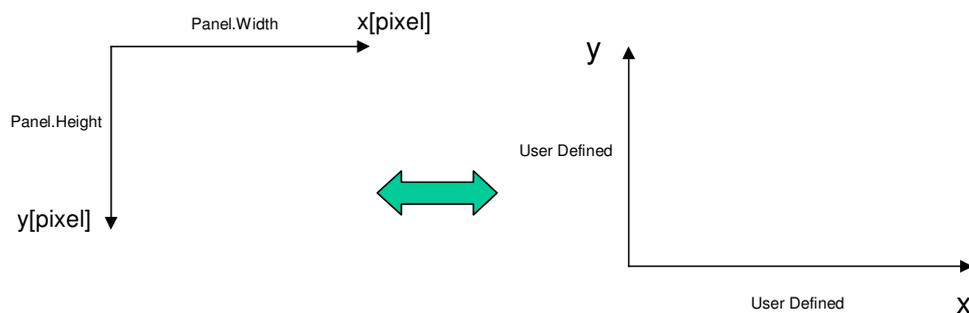


Figure 7: Coordinate Transformation

methods `findLowerCurveSegment(int x, int y)` or `findUpperCurveSegment(int x, int y)` are called. `x` and `y` are the coordinates, where the mouse has been pressed. To determine whether a curve segment has been selected, a virtual rectangle is placed around each curve segment and every rectangle is controlled if the mouse click lies inside it. But as it is difficult to place a rectangle around a curve which is not parallel to x or y axis and as it is even more difficult to determine whether a point lies inside a rectangle whose edges are not parallel to the x or y axis, a coordinate transformation is done. To do so each curve segment is moved

<sup>9</sup>Real coordinates are the coordinates chosen by the user.

to the zero point of the coordinate plan and the end point of the curve segment is rotated in the following way:

$$x_{2new} = x_2 * \cos(\alpha) + y_2 * \sin(\alpha) \quad (1)$$

$$y_{2new} = 0 \quad (2)$$

Figure 8 shows this rotation and movement. The coordinates of the mouse click are moved

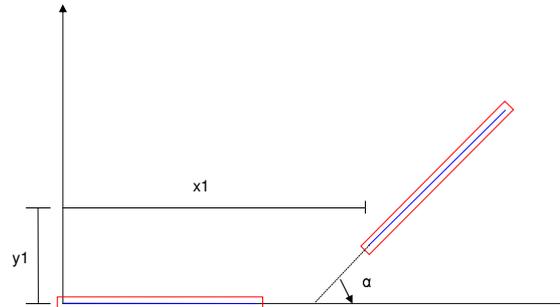


Figure 8: Coordinate Rotation

and rotated by the same parameters. Now a rectangle can easily be placed around the curve segment and it can easily be controlled if the mouse click lies inside the rectangle.

### Class GridDialog

This class opens a new `JInternalFrame`. The user has the possibility to choose the number of squares to be drawn in both axis directions and the number of units per square for both axis. Additionally a `JColorChooser` allows to define the color of the upper and lower curves as well as the background color of the grid.

#### 5.1.2 Task and Resource Containers

When a task or a resource is selected, the following classes derived from `JPanel` are shown:

- source task selected: `SourceContainerTIK` and `SourcePanel`
- regular task selected: `RegularContainerTIK` and `RegularPanel`
- sink task selected: `SinkContainerTIK` and `SinkPanel`
- resource selected: `ResourceContainerTIK` and `ResourcePanel`

The container classes only represent the generic part of the GUI and are empty, whereas the panel classes are filled with objects and placed on the container classes.

The instantiation of these classes is done by the SymTA/S core and therefore cannot be influenced by our library. As the core only creates one instance of each of these classes, all tasks of the same type and all resources have to share one container and one panel. For this reason the context has to be changed every time another task or resource is selected. This is done by using the methods `setCurrentProcess` or `setCurrentResource`, which assign the selected task or resource to the panel. For the selected process the parameters are shown in the panel.

On the other hand every task and every resource has a curve drawer window for every curve. The reason for this is, that the access to each curve drawer window from different tasks of the same type has to be kept. Herewith curves can be edited in several windows simultaneously and the data structure can be forced to save them in the corresponding tasks when a simulation is started. This leads to the structure shown in Figure 9, where several windows are mapped on the same panel.

For this reason the panels have a `Vector` where the actual curve drawer windows are stored. This `Vector` is updated when a new window on a task or a resource is created or when a task

or a resource has been deleted.

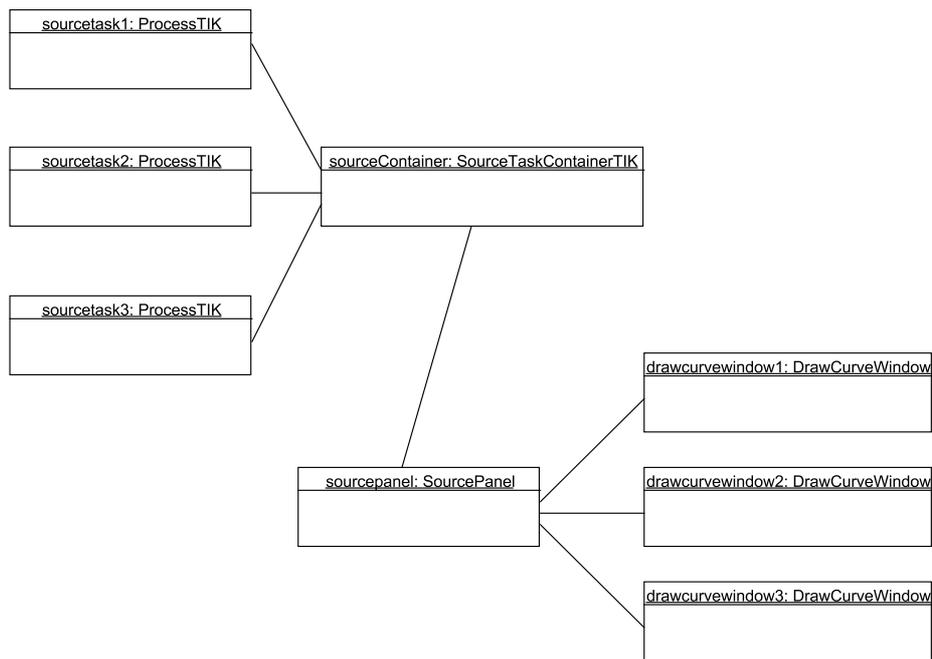


Figure 9: Source Tasks and Appendant Curve Drawer Windows

Additionally for the `RegularTaskContainer` the correct text fields must be shown depending on the resource it is mapped on. This information is taken out from the data structure.

## 5.2 Data Structure

The main purpose of the data structure is to store task and resource information the user has entered or that has been calculated by the tool. A whole set of classes offers this functionality. Figure 10 shows an UML diagram of the classes and their dependencies which will be discussed in the subsequent paragraphs.

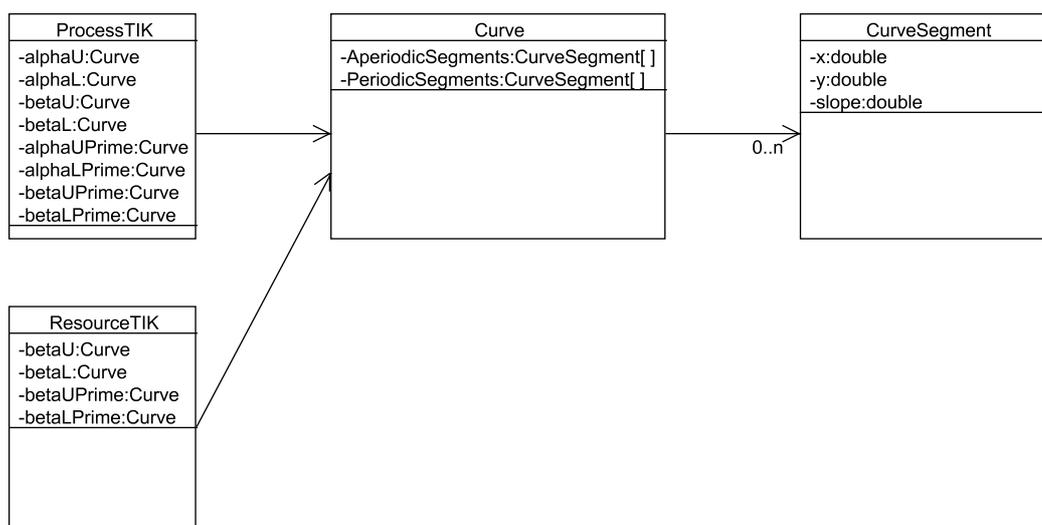


Figure 10: UML Diagram of Data Structure

### 5.2.1 Class Curve

This class represents one curve. This means an instance of this class stores either an upper or a lower curve. The String variable `type` which can be set to "upper" or "lower" determines the curve type to be stored.

A curve is approximated by a number of linear curve segments as shown in Figure 11 and can be composed in different ways. It can be periodic, which means the curve is repeated after a period  $T$ . On the other side it can be aperiodic, which means the last curve segment is extended to infinity. A combination of these two options is possible, too, but not implemented yet. Depending on whether a curve is periodic or aperiodic the curve segments are stored in a `Vector AperiodicCurveSegments` or in a `Vector PeriodicCurveSegments`. The period if needed is saved in the double variable `period`. The methods `isStrictlyPeriodic` and `isStrictlyAperiodic` return true if a curve is strictly periodic respectively strictly aperiodic. If both methods return false, the combination of the two possibilities is used.

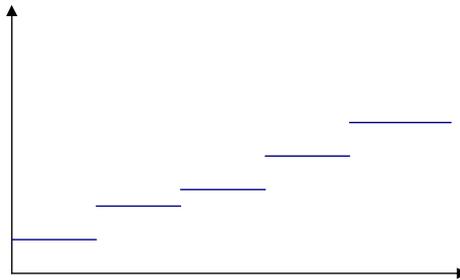


Figure 11: Curve Segments of a Staircase Function

The information on how a curve has to be drawn in the grid is saved in this class, too. The whole grid information including number of squares to be drawn, units per square, curve color and background color are saved in the accordant variables. This offers the advantage the user has to enter the grid properties only once per curve.

A curve can be saved to an XML file. This provides the possibility to make the curves portable and to use them in different programs. To save a curve the method `saveCurve` with the filename as parameter is used. As this method is public it can be called on every instance of `Curve` and the user does not need to know about details on saving a curve into an XML file. Depending on the variable `type` the curve is saved as upper or lower curve. The library used to write the XML file is JDOM. JDOM allows it to create a well structured XML file in an easy and fast way. Appendix C shows an example of an XML file representing a curve.

To load a curve from an XML file an instance of `Curve` must first be created. Then the method `loadCurve` with the name of the XML file can be called and the data is written into the class variables. In this way it can be automatically recognized if a upper or a lower curve has been loaded.

The method `compareCurves` is able to compare two curves by comparing each curve segment. If they are equal, the method returns true, otherwise false.

The method `prune` is used to remove unused curve segments and can be applied to every instance of `Curve`.

### 5.2.2 Class CurveSegment

A curve segment is represented by this class. It can simply store the x and y value of the starting point and the slope assigned to the curve segment. Some more methods offer the option to clone a curve segment or to compare it to another one.

### 5.2.3 Class ProcessTIK

This class represents the different types of tasks. The main idea was to derive it from a generic process as described in Section 4.4.2 and in this way make it replaceable with the process class

from IDA. But as SymTA/S was created in a monolithic approach, the whole tool including the message passing and the whole graph structure had to be adapted to a generic framework. This adaption turned out to be very complex and therefore took much more time than scheduled. As a result the entirely generic solution could not be implemented and another solution close to the desired one had to be found.

The finally chosen option is shown in Figure 12. `ProcessTIK` is derived from `ProcessIDA` instead of `GenericProcess`. In this way all methods and variables needed by the graph structure and the message passing are supplied by the parent class `ProcessIDA` and all methods that work on an object of `ProcessIDA` do also work on an object of `ProcessTIK`. Using this solution the step to an entirely generic solution should be very small and the only drawback is the fact, that the TIK part can only be used if the IDA part is available. This means the TIK library can not be loaded fully independently yet.

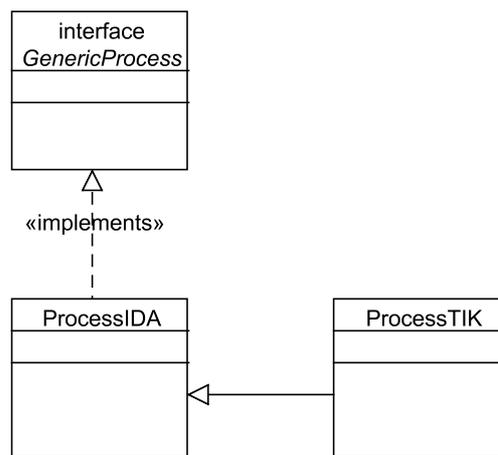


Figure 12: UML Diagram of Process Structure

All functionality that is specific to a TIK task is implemented in this class. Eight `Curve` variables can save all four curve pairs. Whether an object of this class represents a source task, a regular task or a sink task is determined in the int variable `type`, which is set to 0 for a regular task, 1 for a source task and 2 for a sink task. Depending on the task type an object represents, not all `Curve` variables are used and thus can reference to `null`.

A regular task must additionally be able to save the scheduling options. If a TDMA Scheduler is used, the task must get a weight defined in the double variable `weight`, which describes the time share of the resource the tasks get. If a FPS Scheduler is used, the task must get a priority stored in the int variable `priority`. The GUI is able to load automatically the correct scheduling options depending on the selected scheduler by using the methods `getWeight` and `getPriority`.

There are some more parameters needed only by a regular task. On the one hand it is the *Worst Case Execution Time* stored in the double variable `wcet`. This parameter can be chosen by the user. On the other hand the double variables `memory` and `delay`, which are calculated during the analysis, are used.

#### 5.2.4 Class ResourceTIK

For this class a similar solution to the one for the class `ProcessTIK` had to be chosen. Figure 13 shows the corresponding UML diagram.

All methods and variables needed by the graph structure and the message passing are supplied by the parent class `ResourceIDA`.

All functionality specific to a TIK Resource instead are stored in the child class. A beta curve and a beta prime curve can be saved. Every object of this class owns a variable `schedulerTIK` which is set to a FPS Scheduler by the constructor.

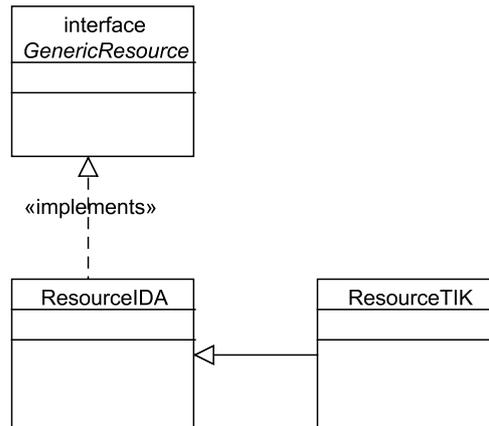


Figure 13: UML Diagram of Resource Structure

### 5.2.5 Interface Drawable

The curve drawer must be able to access curves for editing the classes `ProcessTIK` and `ResourceTIK` in the data structure. For this reason the interface `Drawable` has been introduced. It is implemented by both classes `ProcessTIK` and `ResourceTIK` as shown in Figure 14. The interface guarantees, that the necessary methods to save and store curves are implemented.

The curve drawer accesses the data structure through the interface `Drawable` using a variable of the type `Drawable` in the class `DrawCurveWindow` which can be filled by an object of type `ProcessTIK` and `ResourceTIK`.

Using this solution the curve drawer can be completely generic and does not have to know if it is used in connection with a process or a resource.

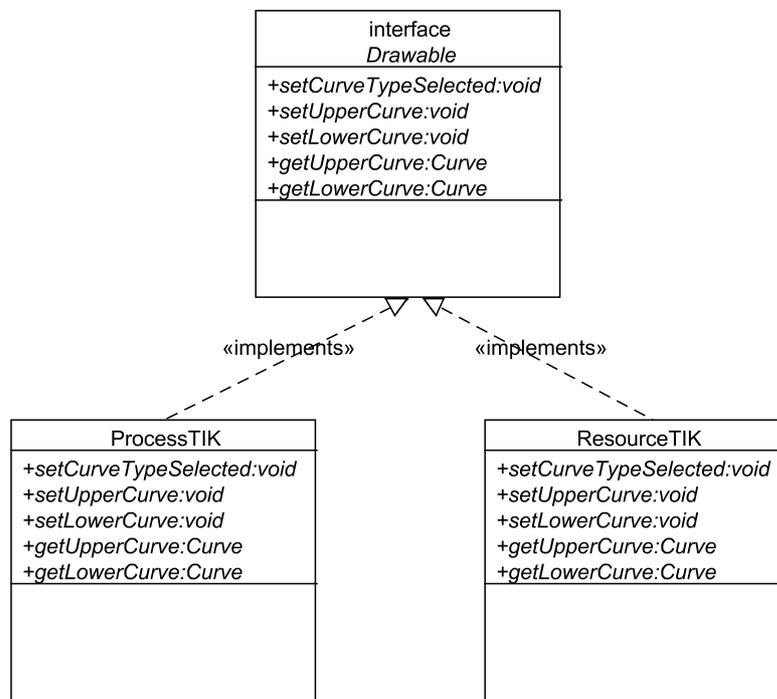


Figure 14: UML Diagram of Interface Drawable

### 5.3 Analysis

The analysis package contains all analysis relevant classes. These are all scheduler classes, the classes, which do the calculation, and the classes, which do the main processing of the analysis.

In this subsection the analysis package is described in detail. But first we provide an explanation how we run with the calculation through the various tasks that the user has drawn in the editor window.

#### 5.3.1 Calculation Flow

Figure 15 shows a simple example with four regular tasks placed on two resources. The tasks T1, T2, T3 and T4 are connected in one line and therefore we call them a *Row*. The tasks T5, T6, T7 and T8 show the second row. T2 and T6 are mapped on resource R1 which uses the scheduling policy Fixed Priority Scheduling (FPS). T6 has priority 1, whereas T2 has priority 2. T3 and T7 are mapped on resource R2 with the scheduling policy Time Division Multiple Access (TDMA) with a weight of 0.6 respectively 0.4.

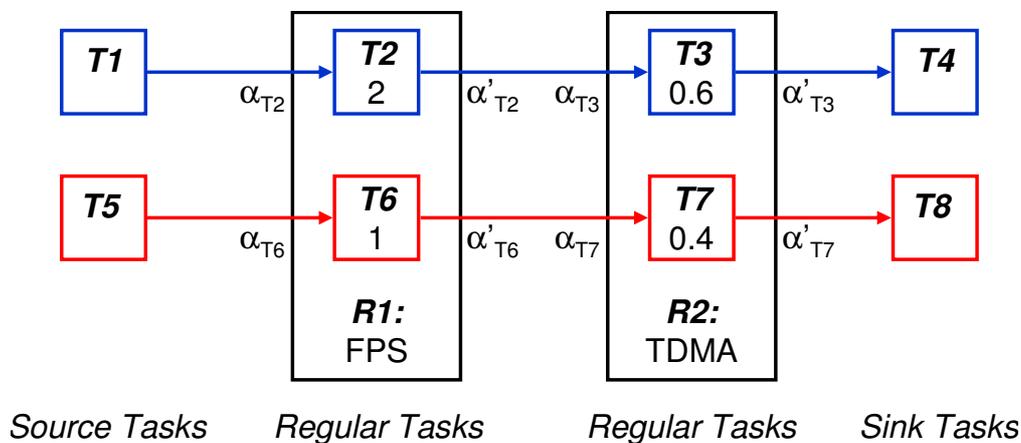


Figure 15: Example to Explain the Calculation Flow Implemented in the Library

T1 contains the original alpha curves, T4 holds the resulting alpha prime curves after the calculation. T2 gets his alpha curves from T1 ( $\alpha_{T2}$ ) and his beta curves come from the resource. The resulting alpha prime curves of T2 ( $\alpha'_{T2}$ ) are the input alpha curves of T3 ( $\alpha_{T3}$ ). The same can be applied to the tasks in the second row.

There are two directions to pass through the tasks. The first direction is along the rows from the left to the right. As soon, as the alpha prime curves are calculated, they can be forwarded to the next task and are used there as alpha curves.

It may happen that not all curves which are needed for the calculation are available and that we cannot continue from the left to the right. A reason for such an interrupt in the calculation flow can be seen in Figure 15. The calculation methods starts at T1 and proceeds to the connected regular task T2 on the right hand. Because we need the resulting beta prime curves on resource R1 from the regular task with priority 1, we cannot continue our calculation and have to stop it here and first proceed on the second row. Therefore we need the second direction, which is from the top to the bottom, or with other words from one row to the next one.

We use a `vector` to retain the information how fare we could proceed in our calculation flow. The `vector` contains the references on the tasks which could be successfully handled, for regular tasks this means that all curves could be calculated successfully. The `vector` contains as many elements as rows exist and is initialized together with the sources.

In our example from the former paragraph the first element has not been replaced by a reference on T2 because we could not successfully calculate the curves to T2 and it shows that we have started with this row and have been stopped at T1 and therefore have to continue there

after calculating in row two. In the last paragraphs we have picked out a part at the beginning of the calculation flow. The other tasks are handled in a similar way. We have now introduced the two directions in which we need to proceed our calculation. The description of the implementation of this concept is given in the next subsection.

### 5.3.2 Class Analysis

The method `performAnalysis` is described in this paragraph. Figure 16 shows the program flow of this method.

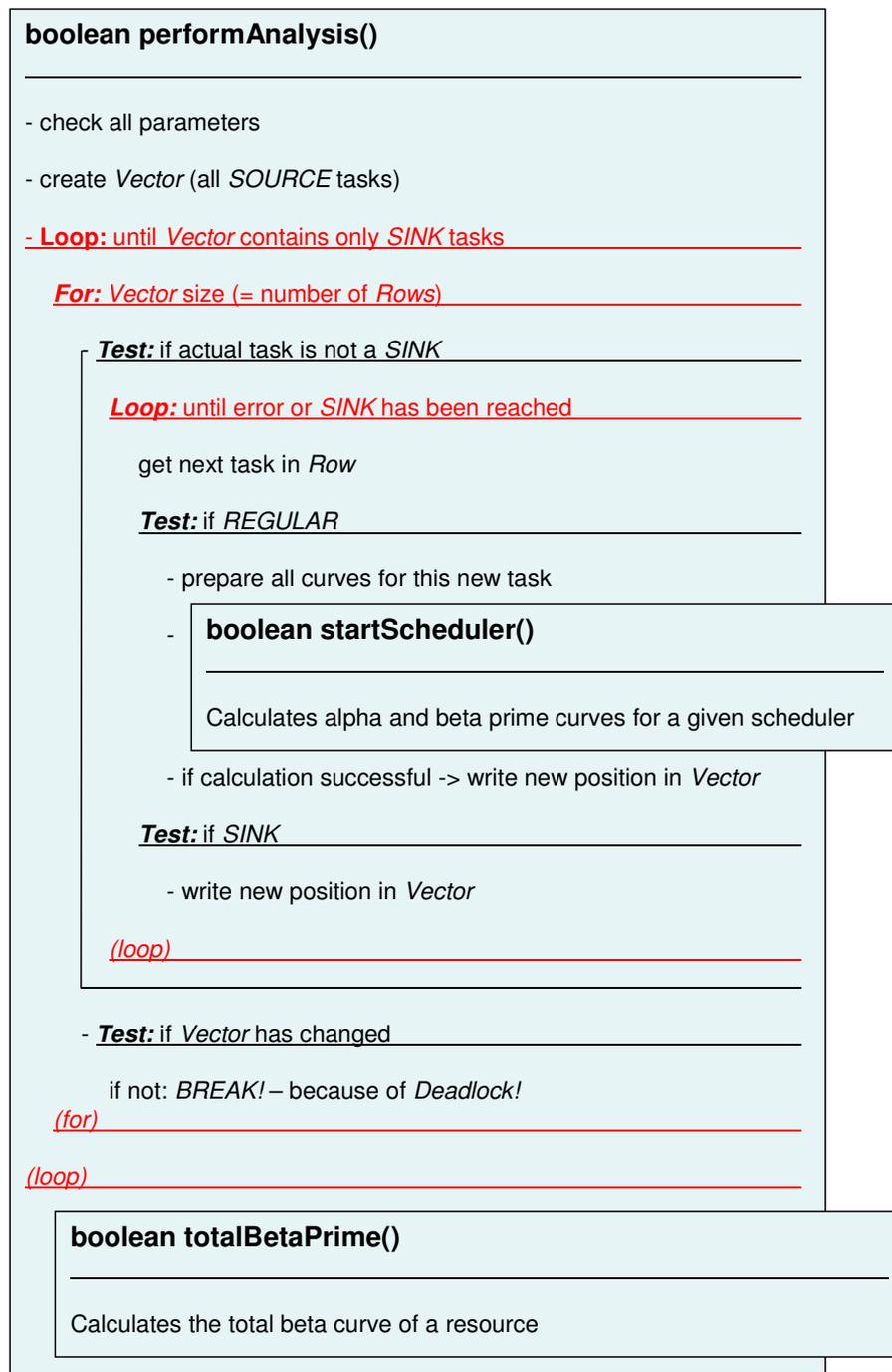


Figure 16: Architecture of the Method Analysis

There are three nested loops. In Figure 16 the three loops are colored red. The first loop is a while-loop and is repeated as long as not all sinks are reached. When all sinks are reached, the `vector` contains only sink tasks. Within this loop there is an if-statement, which might break this first loop. If all elements of the `vector` have not changed during a loop, the if statement is true and herewith the loop will be broken. This behaviour shows a deadlock. This means not all sink tasks are reached yet but the `vector` does not change anymore. This may occur in the case of the example given in Figure 17. The resource uses a FPS policy and the tasks have the priorities 2 and 1.

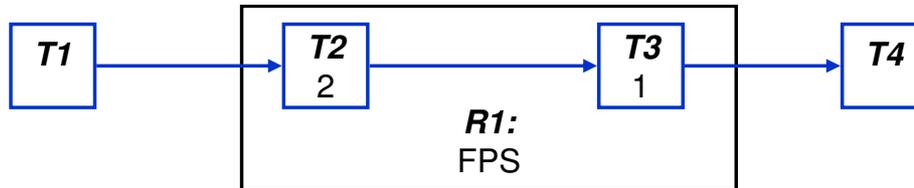


Figure 17: Example of a Deadlock

The second loop, is a for-loop and is repeated as many times as rows exist. It starts with the first element of the `vector` and runs through all elements. These two outer loops represent the second dimension introduced at the end of Section 5.3.1.

The first dimension is represented by the innermost loop, a while-loop. This loop is repeated as long as the end of a row, a sink, is not reached and no error has occurred. If the calculation could not be finished, for example because of a reason discussed in Section 5.3.1, the variable `calcSuccess` will be set to `false` and the loop will be stopped.

In the inner loop there are some if-statements, which test if the next task is a regular or a sink task and based on this the decision is taken if a calculation has to be done or if the end of the row has been reached. If the current task is a regular task, the method `startScheduler` is called, which is described in Section 5.3.3.

Figure 18 shows an abstract program flow of the environment of the analysis class. The three loops described in the previous paragraph are summarized in the *Calculation* part of Figure 18 starting at line "while (not all sinks are reached)". This while loop is the first of the three mentioned loops.

The user clicks on the *Analysis Button* and herewith the analysis is started. The next steps are preparations for the analysis as it can be seen in Figure 18. Out of this method the method `performAnalysis` is started, which has been described at the beginning of this section. The task "check all parameters" in Figure 16 is quite a big part of the class `performAnalysis` and is shown in Figure 18.

SymTA/S offers a useful possibility to print out information, warnings and errors. The following line prints an error message into the output window of the SymTA/S tool:

```
MessageHandler.printToOutput("error!", 0);10
```

Figure 18 shows all the tests which are made and the resulting messages. Messages are generated in the part, where scheduling parameters, curves and other elements are checked as well as in the calculation part. The scheduling parameters depend on the scheduling policy and the method `testSchedulingParameters` is therefore implemented in the scheduling classes, as described in Section 5.3.3.

<sup>10</sup>The integer value at the end of this statement, gives the message typ. 0 stands for an error message in red, 1 for a warning in blue and 2 for other information in black.

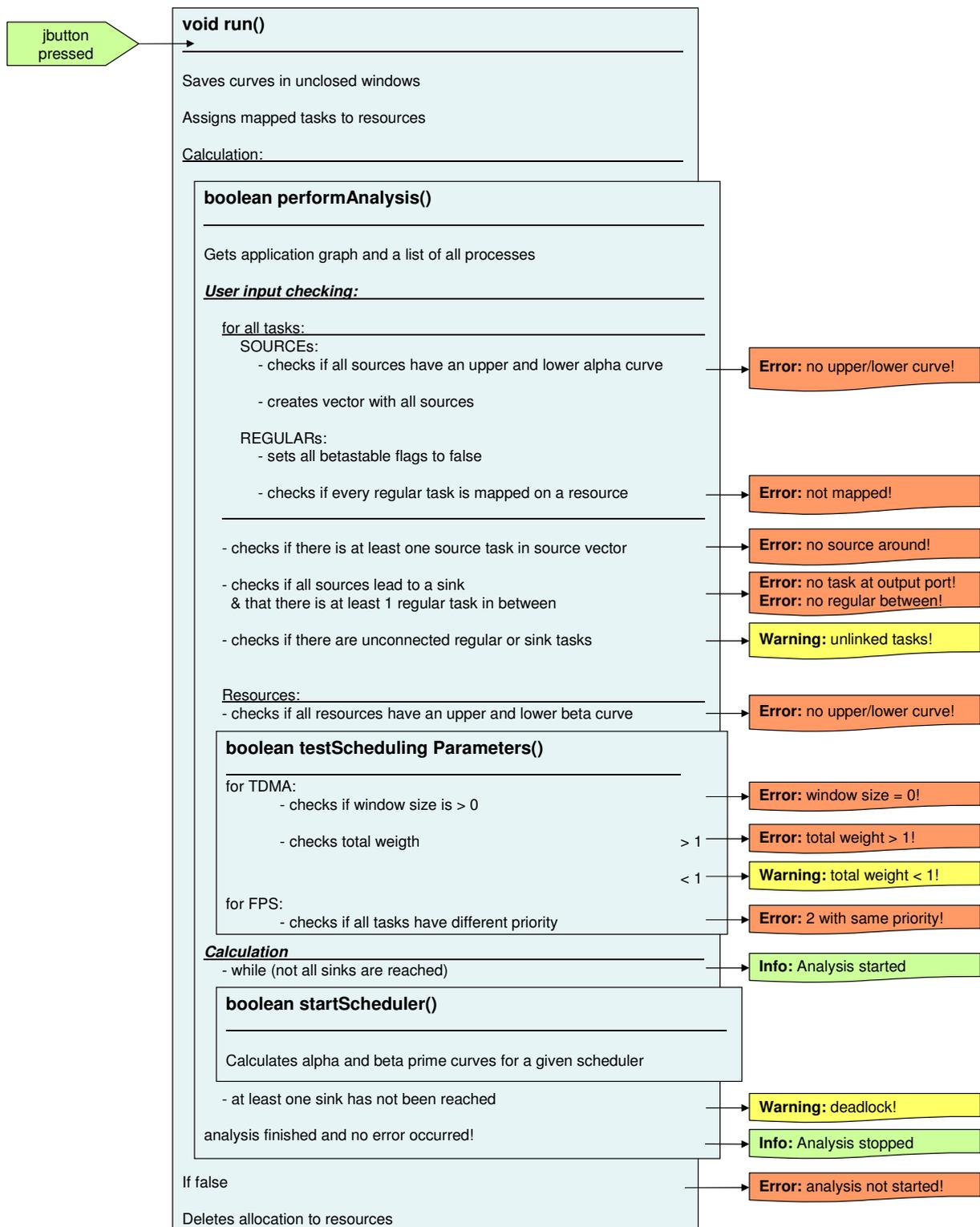


Figure 18: Architecture of the Error Handling

### 5.3.3 Scheduler

The scheduler is related to everything which has to do with the scheduling policy. The UML diagram in Figure 19 shows how the scheduler class is embedded into the other classes.

There is a general scheduler class, which can be found in the center of the UML diagram. This class contains among other methods the three methods called `startScheduler`,

`computeFinalBetaPrime` and `testSchedulingParameters`:

**startScheduler:** This method is called from the method `performAnalysis`<sup>11</sup>. The first part of the method decides if the calculation on a certain regular task can be done with the given information, then does prepare all input curves and finally calls the calculation methods.

**computeFinalBetaPrime:** Calculates the resulting beta prime curves on each resource and is called at the end of the method `performAnalysis`.

**testSchedulingParameters:** This method is designed to test the scheduling parameters and is called from the method `performAnalysis`.

The methods mentioned above are scheduler dependent and therefore overwritten in the classes `FPSScheduler` and `TDMAScheduler`.

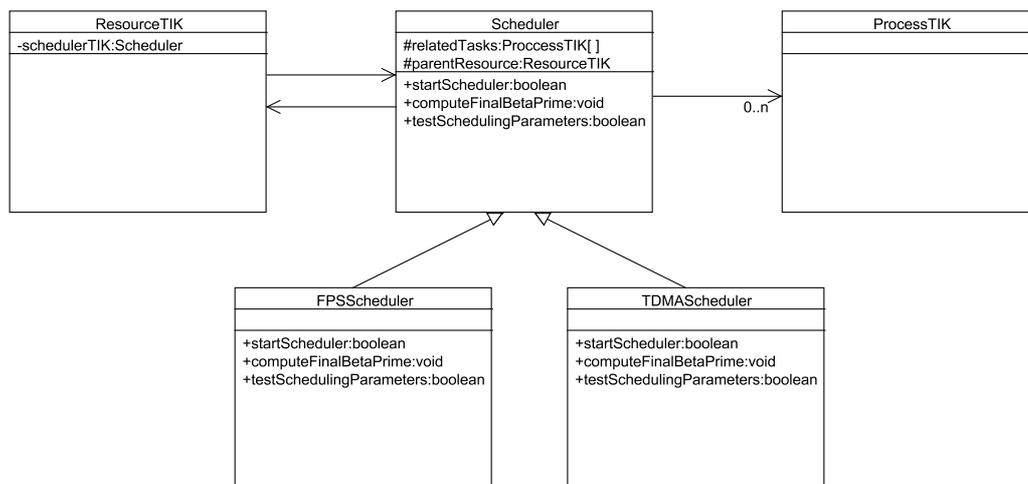


Figure 19: UML Diagram of the Environment of Scheduler Class

For each scheduling policy a separate scheduler class is implemented, which extends `Scheduler` as Figure 19 shows. Consequently they have to implement the three methods mentioned above. In Section 5.3.5 and Section 5.3.4 the implementation of the two scheduling policies, which have been chosen for the first version of this library, is explained in more details.

The Scheduler contains also the protected `Vector` `relatedTasks`, which contains all tasks, which are mapped on one resource and therefore use the same scheduler.

A further important variable is `parentResource` from the type `ResourceTIK`. `parentResource` contains a reference to the parent resource the scheduler runs on. The UML diagram in Figure 19 shows these two dependencies.

#### 5.3.4 FPS Scheduler

The implementation of the `FPSScheduler` class concentrates on the three methods `testSchedulingParameters`, `startScheduler` and `computeFinalBetaPrime` as explained in the previous paragraph. Partitioned in three paragraphs we will explain the ideas behind the implementation.

##### testSchedulingParameters

The FPS policy schedules the order of the tasks based on the priority of each task. The priority is the only parameter which has to be set and accordingly has to be tested in this method.

<sup>11</sup>The method `performAnalysis` is described in Section 5.3.2.

The test criteria is, if all tasks on one resource have different priorities.<sup>12</sup> The method contains two nested loops which run through all tasks and compare them to all the other ones. Figure 18 contains this error message, too.

#### **startScheduler**

The method `startScheduler` is called out of the method `performAnalysis` as it can be seen in Figure 16, too. Before invoking the `CurveTransform` classes, we first have to check if we can do the calculation. Therefore we check if this task has the smallest priority. In this case, we get the beta curves directly from the resource and we can start the calculation. If there is a task with a smaller priority, than the current one gets the beta curves from the previous one. But first we have to check if the beta curves of the previous one are already calculated correctly. The method `getStableBetaPrime()` called on the the previous task tells us if these beta curves can be used or not. If we cannot use these beta curves, what means, that the task with the smaller priority has not been calculated, we cannot do a calculation step and return `false`. Otherwise we get the beta curves from the previous task and start the analysis.

#### **computeFinalBetaPrime**

With FPS the resulting beta prime curves on a resource are the beta prime curves of the task with the lowest priority running on it. Therefore this method checks all task on this resource and stores the beta curves of the task with the lowest priority in the resource class.

### **5.3.5 TMDA Scheduler**

The structure of the `TDMA Scheduler` class is similar to the `FPSScheduler` class.

#### **testSchedulingParameters**

When the user chooses a TDMA scheduling policy, the parameter which reallocates the resource is the weight of a task. The total weight is normally 1.0. This method adds all weights on a resource up and checks the result. If the totalized weight is greater than 1.0, the analysis will be stopped. If it is smaller then 1.0 a warning will be printed out.<sup>13</sup>

The second parameter which has to be tested is the window size. The window size has to be greater than 0.0 if the window size is evaluated, otherwise we do not care about the entered value.

#### **startScheduler**

The resource capability is split based on the weight. Therefore a calculation can always be started, contrary to the FPS scheduler.

There are two possible scenarios now. The first one is, that we evaluate the window size and calculate the weighted beta curves regarding the window size. Such curves can be seen in Figure 20.<sup>14</sup> On the other hand the user can choose to weight the beta curves without evaluating the window size, which can be seen in Figure 21.

After having finished the preparation of all needed curves we can calculate the curves using again the methods of the `CurveTransform` class.

#### **computeFinalBetaPrime**

If we have not evaluated the window size, we can calculate a beta prime curves, which are the sum of all beta prime curves on this resource. Otherwise the tool does not calculate a resulting beta prime curves.

<sup>12</sup>The analysis is only started, if there are no task on a resource with the same priority. Otherwise the analysis would not work properly.

<sup>13</sup>A totalized weight of smaller then 1.0 means that there are other tasks which run on this resource, which are not drawn here.

<sup>14</sup>The method accepts for the case "evaluate window size" only curves which consist of exactly one curve segment.



Figure 20: Weighted Beta Curves with the Option *Evaluate Window Size* and a Window Size of 1.0



Figure 21: Weighted Beta Curves without the *Option Evaluate Window Size*

### 5.3.6 Class `WCET_calculation`

The class `WCET_calculation` is a very simple class and consists only of two methods. The *Worst Case Execution Time* (WCET) influences the alpha curves and the resulting alpha prime curves as described in Section 2.3.2.

The current version of the library provides the possibility to enter a value for the WCET for each task. The two methods in this class provide multiplication and division of an alpha curves with this chosen WCET value. They are called out of the scheduler, the multiplication at the beginning and the division at the end of the calculation process.

### 5.3.7 Package `singlenode`

The package `ch.ethz.ee.tik.rtc.analysis.singlenode` contains all classes which do calculations based on the TIK analysis method on a single node. The most important class is the `CurveTransform` class, which can be used to call calculations. The other classes are only used within the package.

The class `CurveTransform` contains the following methods:

**`getLowerArrivalPrime(...)`** returns the lower alpha prime curves based on the alpha lower, beta lower and beta upper curves.

**`getUpperArrivalPrime(...)`** returns the upper alpha prime curves based on the alpha upper, beta lower and beta upper curves.

**`getLowerServicePrime(...)`** returns the lower beta prime curves based on the beta lower and alpha upper curves.

**`getUpperServicePrime(...)`** returns the upper beta prime curves based on the beta upper and alpha lower curves.

**`getDelay(...)`** returns the delay of a node based on the alpha upper and beta lower curves.

**`getMemory(...)`** returns the memory consumption of a node based on the alpha upper and beta lower curves.

**`addCurves(...)`** can be used to add two curves.

**`multCurve(...)`** can be used to scale curves with a factor.

This package has not been implemented by us and we therefore do not explain any further details.

## 6 Short user manual

### 6.1 How To Use?

This section will give a short introduction on how to use SymTA/S focusing on the new features that have been added by the TIK library.

#### 6.1.1 Tasks and Resources

The user has the possibility to add three different tasks by clicking on the appropriate icon in the tool bar:

- a source task,
- a regular task,
- and a sink task.

Afterwards he can select a task and the properties of the selected task are shown in the task window and can be edited.

Figure 22 shows an example of a source task. The only thing that can be edited are the alpha curves by pressing on the button "Edit Alpha Curves". A new curve drawer window described in Section 6.1.2 will open.

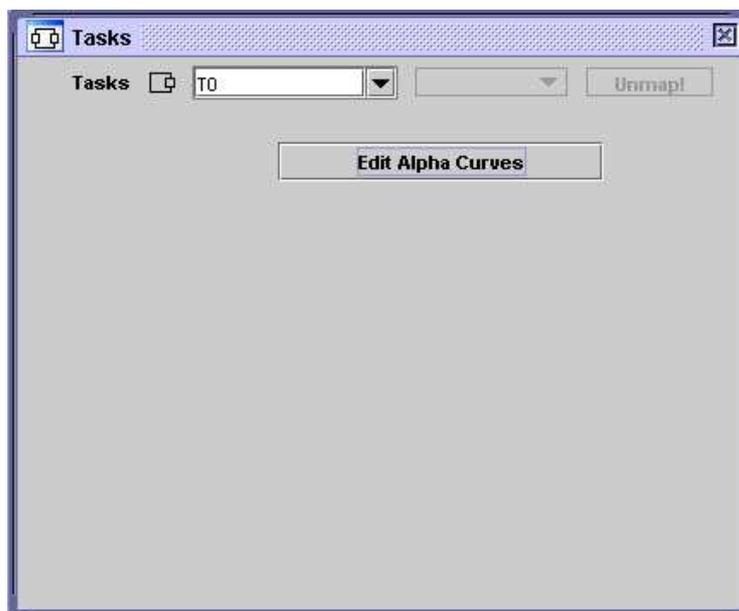


Figure 22: Properties of a Source Task

Figure 23 shows an example of a regular task. Here, the user has the possibility to view all four curves by pressing on the buttons "Show Alpha Curves", "Show Beta Curves", "Show Alpha Prime Curves" and "Show Beta Prime Curves". The worst case execution time of the task can be entered in a text field. The important thing here as for all other text fields is, that an input has to be confirmed by pressing the return key.

After a calculation the calculated memory and delay are shown in the two lowest text fields.

If a resource is available, a regular task can be mapped on it by selecting the resource in the combo box. The selected scheduling policy on the resource will also be shown in the task properties and depending on it different options can be chosen.

Using TDMA, the weight, which describes the share of the resource and can vary between 0 and 1, must be entered. If a calculation is started, it is controlled if the summation of all weights on a resource equals 1. In case it is smaller than 1, a warning is printed out and the dispensable resource share remains unused.

Using FPS, the priority of a task must be entered. After starting a calculation it is controlled if there are not any tasks with the same priority on the same resource.

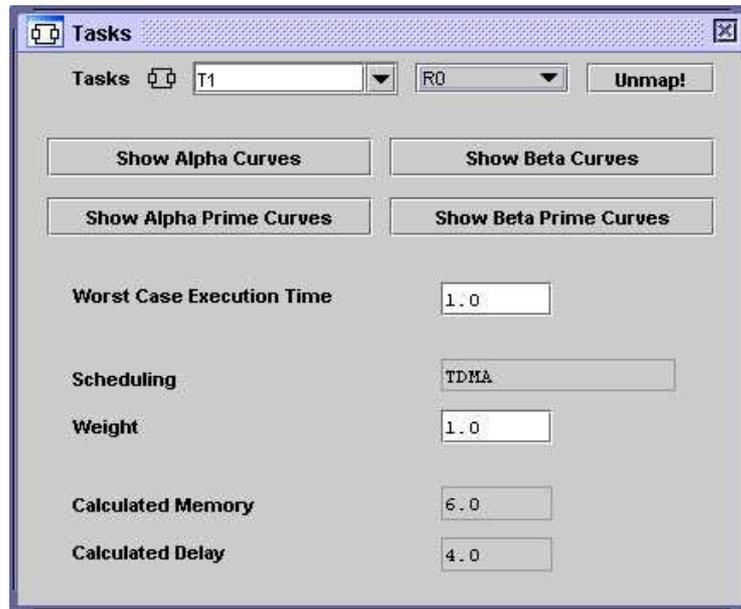


Figure 23: Properties of a Regular Task

Figure 24 shows an example of a sink task. Here, the resulting alpha prime curves can be viewed by pressing on the button "Show Alpha Prime Curves".

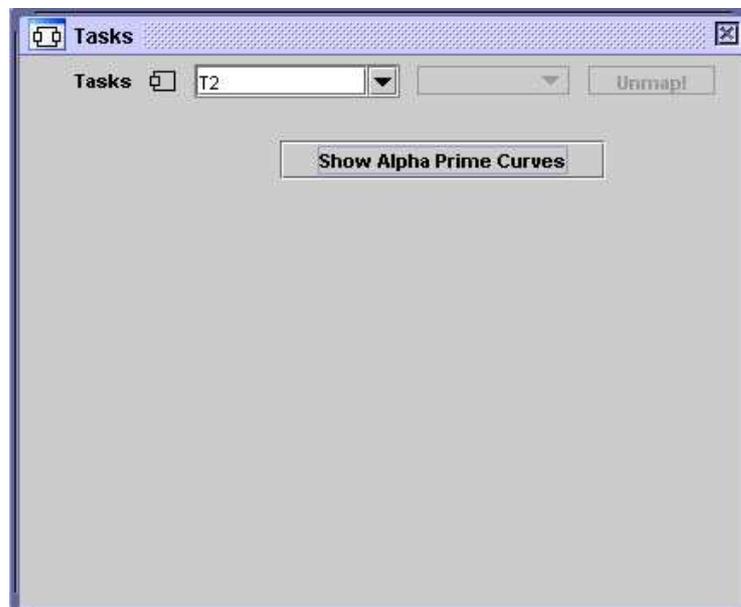


Figure 24: Properties of a Sink Task

The properties of a resource can be chosen in the resource window as shown in Figure 25. The beta curves can be entered by pressing the button "Edit Beta Curves". The resulting beta prime curves on the resource are calculated depending on the scheduling policy and can be shown by pressing the button "Show Beta Prime Curves".

The scheduling policy can be chosen in a combo box. At the moment TDMA and FPS are available.

If TDMA is selected, two different calculation models are supported. The first model evaluates the window size, the second one does not.

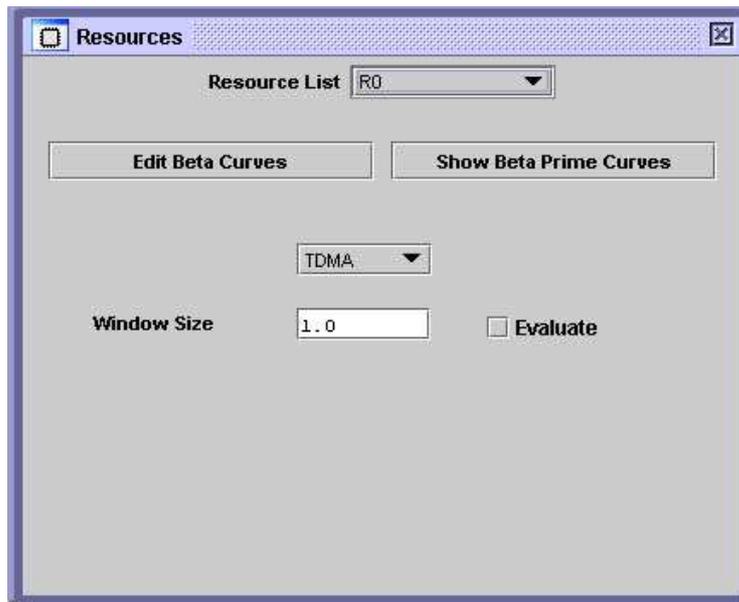


Figure 25: Properties of a Resource

### 6.1.2 Curve Drawer

Figure 26 shows an example of an editable curve drawer window. All icons in the tool bar from the left to the right are described in this paragraph.

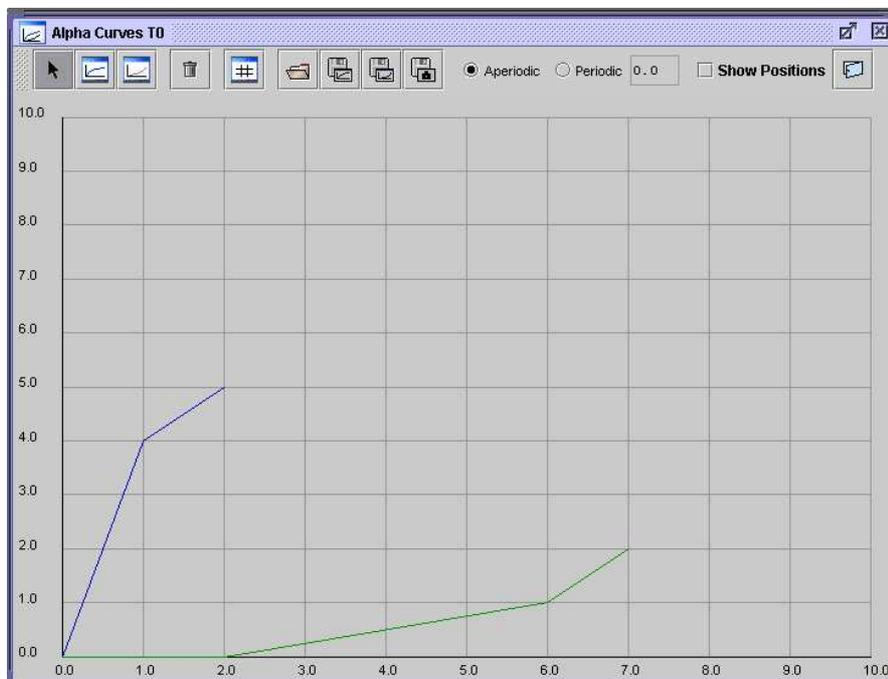


Figure 26: Curve Drawer Window

Curves can be painted by selecting the icons "Draw Upper Curve" or "Draw Lower Curve".

Afterwards a single curve segment or a set of curve segments can be selected, if the "select" icon is active. The selected elements can be moved or deleted by pressing the "Delete" icon. The "Grid Properties" icon allows to change the grid properties in a new window.

The next four icons are used to load and save curves to an XML file or to save the curves as a screen shot into a png file.

In the radio button group it is decided, whether a the curves are periodic or aperiodic. If periodic is selected, the period text field becomes editable.

The check box "Show Positions" allows to show the positions of the mouse cursor and all selected curve segments.

By clicking on the "Close Window" icon or the cross icon in the upper right corner the window is closed and the curves are saved to the data structure. If a curve is loaded from the data structure and shown in the curve drawer window, the last curve segment gets automatically the length 1 in the x direction, because the ending point is not defined.

## 6.2 Analysis Example

In this section an example of a simulation which has been done using the new TIK library will be presented. Figure 27 shows the structure of the tasks and resources.

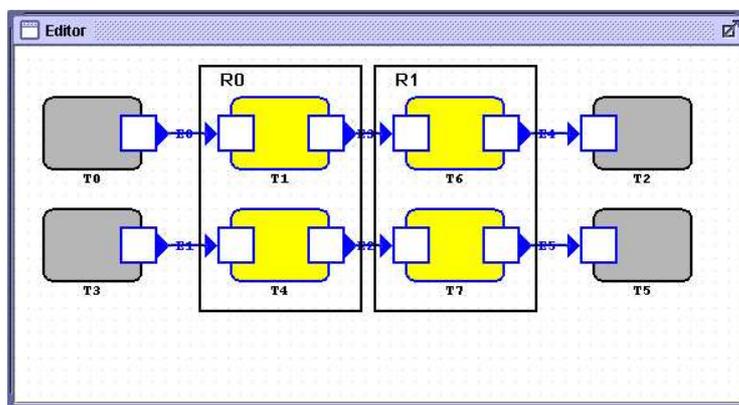


Figure 27: Simulation Example

T1 uses the alpha curves shown in Figure 28. T3 uses the alpha curves shown in Figure 29.

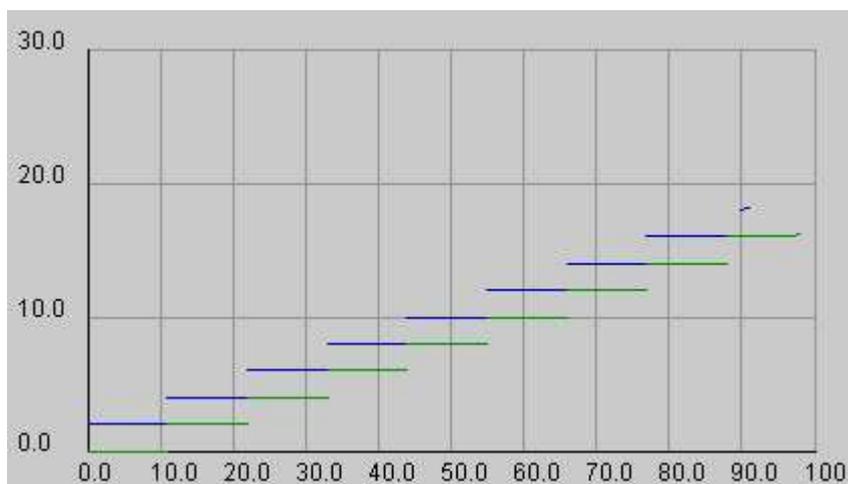


Figure 28: Alpha Curves Task T1

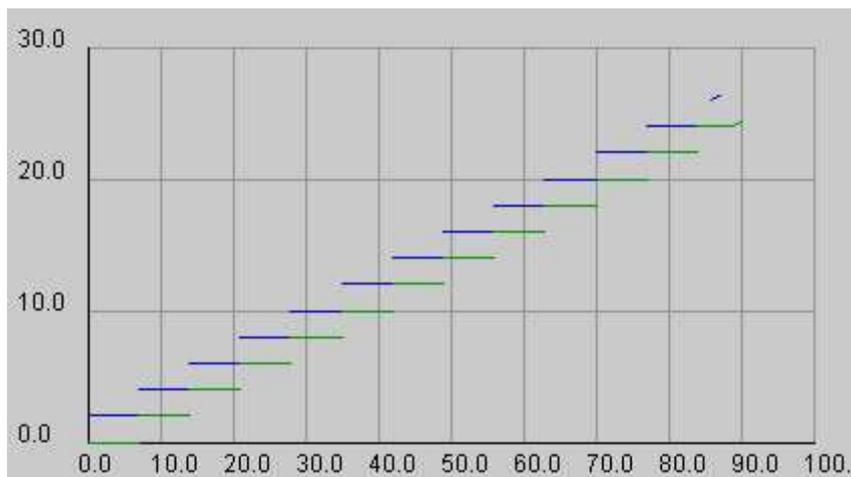


Figure 29: Alpha Curves Task T3

R0 has the following properties:

- FPS Scheduler
- mapped tasks: T1, T4
- priority T1: 1
- priority T4: 2
- beta curves shown in Figure 30

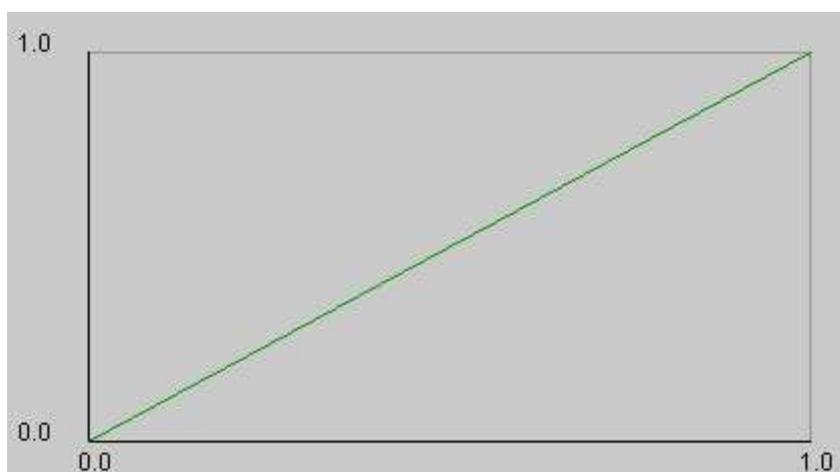


Figure 30: Beta Curves Resource R0 and R1 (Upper and lower curves are congruent.)

R1 has the following properties:

- TDMA Scheduler
- mapped tasks: T6, T7
- weight T6: 0.5
- weight T7: 0.5

- evaluate: not selected
- beta curves shown in Figure 30

The resulting alpha prime curves can be seen in Figure 31 for T2 and in Figure 32 for T5.

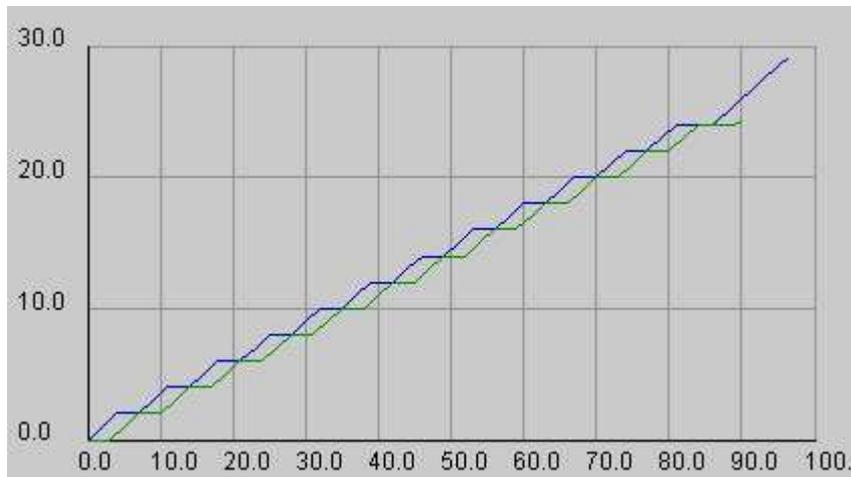


Figure 31: Alpha Prime Curves Task T2

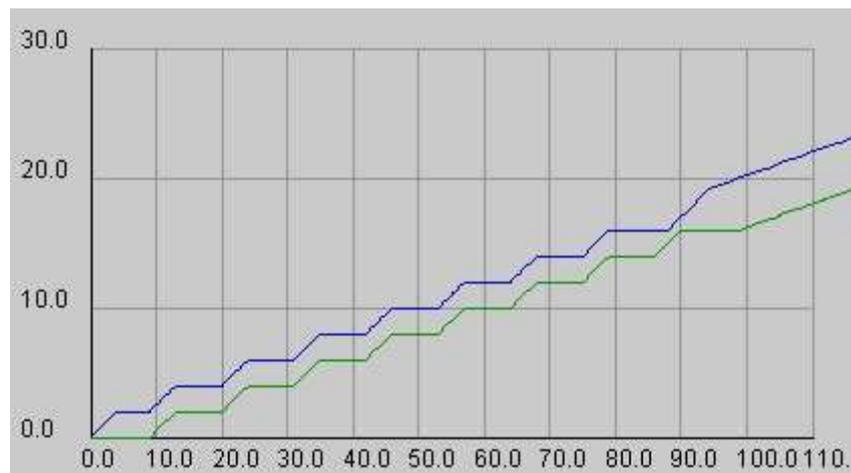


Figure 32: Alpha Prime Curves Task T5

## 7 Outlook

The generic approach of the solution which has been pursued offers the possibility to improve the tool.

The first step that will surely have to be taken is the implementation of the completely generic data structure. As soon as the generic framework is available, it should be possible to adapt the concerned classes in an easy manner. As the data structure classes are already prepared for this solution, some small changes will be necessary.

Probably, new scheduling policies will be desired. In this case a new class derived from `Scheduler` can be added and the methods specific to the new scheduling policy must be overwritten. Some modification in the GUI container for the resource will also be necessary, but totally the modifications should be very small as the structure of the resource is already prepared to add new schedulers.

A further problem to deal with is the improvement of the calculation performance. Simulations have shown, that a calculation can take a not negligible amount of time. An optimization of the calculation algorithms or a limitation to a certain number of curve segments which is not defined yet would surely improve the performance.

## 8 Summary

During this thesis a library to the SymTA/S tool has been developed to use the *Real Time Calculus* methods efficiently. A generic approach has been almost totally implemented. The requirements on the library could be fulfilled and the two scheduling policies *Fixed Priority Scheduling* and *Time Division Multiple Access* have been implemented successfully.

The program contains a useful tool to draw curves. The curves drawn can be used for the analysis or be stored into XML files to use them in other programs. The major part of the work was to design a userfriendly solution and to develop a comprehensive error handling.

The current version of the library provides a stable solution which can be used to gain first experiences with this new tool.

## **A Acknowledgements**

Various helpful comments and ideas were received from Simon Künzli.

Furthermore, mainly lively discussions with colleagues created input to the work.

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## C Example of a Curve XML File

The example below shows an XML file of an upper curve, as it has been stored in the *Curve Drawer Window*.

```
<?xml version="1.0" encoding="UTF-8"?>
<curvecontainer xunit="1.0" yunit="1.0" xgrid="10" ygrid="10">
  <curve name="uppercurve" type="upper">
    <aperiodic burstlength="0.0">
      <curvesegment x="0.0" y="2.0" slope="0.0" />
      <curvesegment x="11.0" y="4.0" slope="0.0" />
      <curvesegment x="22.0" y="6.0" slope="0.0" />
      <curvesegment x="33.0" y="8.0" slope="0.0" />
      <curvesegment x="44.0" y="10.0" slope="0.0" />
      <curvesegment x="55.0" y="12.0" slope="0.0" />
      <curvesegment x="66.0" y="14.0" slope="0.0" />
      <curvesegment x="77.0" y="16.0" slope="0.0" />
      <curvesegment x="90.0" y="18.0" slope="0.18181818182" />
    </aperiodic>
    <periodic period="0.0" />
  </curve>
</curvecontainer>
```

## D Libpreferences.xml

The Libpreferences.xml file defines which modules are used as described in Section 4.

```
<?xml version="1.0" encoding="UTF-8"?>
<!--
  $Id: libpreferences.xml,v 1.1.1.1 2004/06/03 16:31:15 kuenzli Exp $

  project          : SPI / SYMTA
  copyright        : (C) IDA 2002

-->

<Symta-S>

  <!-- here we define pointers to all classes that are used for the GUI -->
  <gui>
    <RegularTaskContainer>
      ch.ethz.ee.tik.rtc.gui.RegularTaskContainerTIK
    </RegularTaskContainer>
    <SourceTaskContainer>
      ch.ethz.ee.tik.rtc.gui.SourceTaskContainerTIK
    </SourceTaskContainer>
    <SinkTaskContainer>
      ch.ethz.ee.tik.rtc.gui.SinkTaskContainerTIK
    </SinkTaskContainer>
    <ResourceContainer>
      ch.ethz.ee.tik.rtc.gui.ResourceContainerTIK
    </ResourceContainer>
    <EventStreamContainer>
      ch.ethz.ee.tik.rtc.gui.EventStreamContainerTIK
    </EventStreamContainer>
  </gui>

  <!-- classes used as datastructures -->
  <datastructure>
    <GenericProcess>
      ch.ethz.ee.tik.rtc.datastructure.ProcessTIK
    </GenericProcess>
    <GenericResource>
      ch.ethz.ee.tik.rtc.datastructure.ResourceTIK
    </GenericResource>
    <GenericInputPort>
      org.spiproject.lib.datastructure.InputPortIDA
    </GenericInputPort>
    <GenericOutputPort>
      org.spiproject.lib.datastructure.OutputPortIDA
    </GenericOutputPort>
    <GenericEventStream>
      org.spiproject.lib.datastructure.EventStreamIDA
    </GenericEventStream>
    <GenericEventModel>
      org.spiproject.lib.datastructure.EventModelIDA
    </GenericEventModel>
  </datastructure>

  <!-- classes used for analysis -->
  <analysis>
    <GenericAnalysis>
```

```
    org.spiproject.lib.analysis.AnalysisIDA
  </GenericAnalysis>
</analysis>

<!-- Here we define which of the buttons and menu points in the SymTA/S
      tool are enabled/disabled -->
<settings>
  <!-- to be defined... -->
</settings>

</Symta-S>
```